

CAIET DE PRACTICĂ

Realizat în cadrul

Proiectului Erasmus +, Domeniul Formare profesională (VET), **New skills for new jobs – RobotGO**, Nr. **2022-1-RO01-KA122-VET-000073693**, finanțat de Uniunea Europeană în cadrul Programului Erasmus+.

NUMELE:

IACINSCHI SEBASTIAN

LUCRAREA 1 – Blinking LED

Scopul lucrării: Realizarea unui montaj, utilizând o placă Arduino, astfel încât un LED să-și modifice starea (aprins/stins) la fiecare secundă.

Materiale:

Arduino UNO



x 1

Breadboard (generic)



x 1

LED (generic)



x 1

Conductori



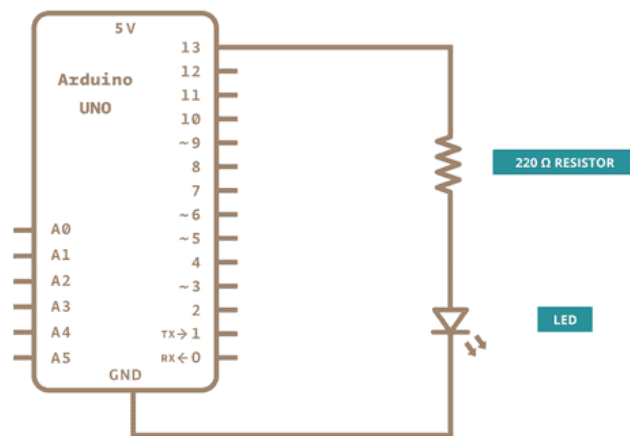
x 1

Rezistență de 220 ohm

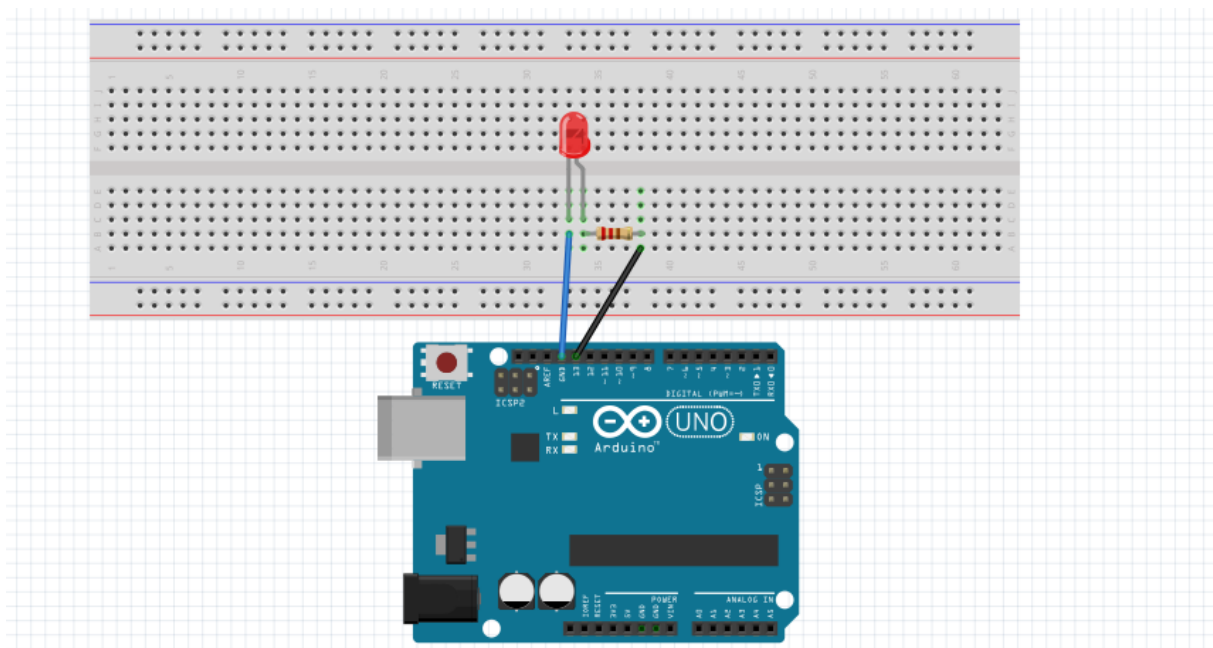


x 1

Schema electrică:



Montaj:



Cod:

```
void setup() {  
  // initializarea pinului 13  
  pinMode(13, OUTPUT);  
}  
  
void loop() {  
  digitalWrite(13, HIGH);  
  delay(1000);  
}
```

```

digitalWrite(13, LOW);
delay(1000);
}

```

LUCRAREA 2 - SEMAFOR

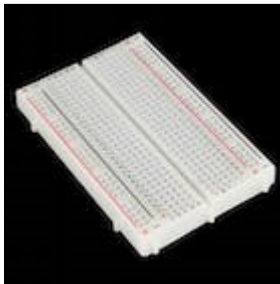
SCOPUL LUCRĂRII: Construirea unui montaj cu 3 led-uri (verde, galben, roșu) care să se aprindă fiecare concomitent pentru o anumită durată.

Materiale:

Arduino UNO



x 1



Breadboard (generic)

x 1

LED (generic)



x 3

Conductori



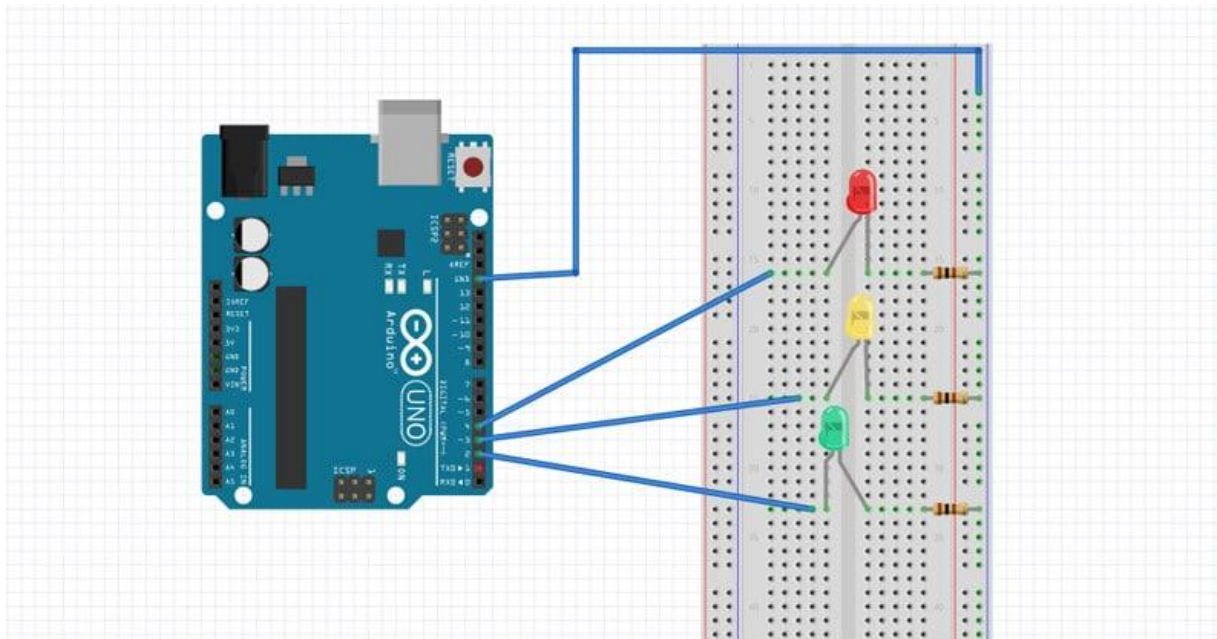
x 1

Rezistență de 220 ohm



x 1

SCHEMA ELECTRICA



COD :

// variables

int GREEN = 2;

int YELLOW = 3;

int RED = 4;

int DELAY_GREEN = 5000;

int DELAY_YELLOW = 2000;

int DELAY_RED = 5000;

// basic functions

void setup()

{

pinMode(GREEN, OUTPUT);

pinMode(YELLOW, OUTPUT);

pinMode(RED, OUTPUT);

}

void loop()

{

green_light();

delay(DELAY_GREEN);

yellow_light();

delay(DELAY_YELLOW);

red_light();

delay(DELAY_RED);

}

```
void green_light()
{
  digitalWrite(GREEN, HIGH);
  digitalWrite(YELLOW, LOW);
  digitalWrite(RED, LOW);
}
```

```
void yellow_light()
{
  digitalWrite(GREEN, LOW);
  digitalWrite(YELLOW, HIGH);
  digitalWrite(RED, LOW);
}
```

```
void red_light()
{
  digitalWrite(GREEN, LOW);
  digitalWrite(YELLOW, LOW);
  digitalWrite(RED, HIGH); }
}
```

LUCRAREA 3– CONSTRUCTING YOUR OWN ROBOT

Scopul lucrarii: Construirea unui robot care sa urmărească o linie neagră.

Materiale:

Arduino UNO



× 1



Breadboard (generic)

× 1

Motor driver



x 1

Conductori



x 1

Motor



x 2

Baterii



x 4

Rotile



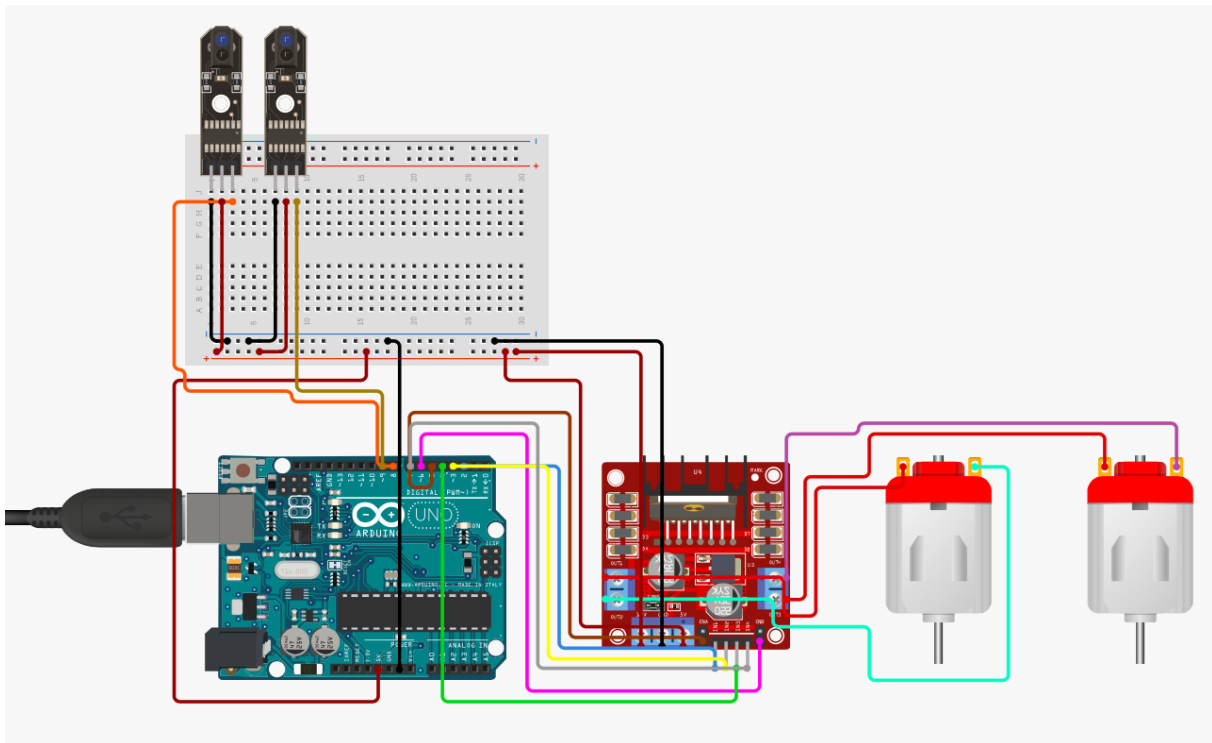
x 2

Senzori



x 2

Schema electrică + montaj



COD:

```
int LM1 = 3, LM2 = 5, RM2 = 6, RM1 = 9;
```

```
int sp1= 160;
```

```
int sp2= 200;
```

```
void setup() {
```

```
  pinMode(A0, INPUT);
```

```
  pinMode(A1, INPUT);
```

```
  pinMode(LM1, OUTPUT);
```

```
  pinMode(LM2, OUTPUT);
```

```
  pinMode(RM1, OUTPUT);
```

```
  pinMode(RM2, OUTPUT);
```

```
  Serial.begin(9600);
```

```
}
```



```
void loop() {  
    int senz2 = digitalRead(A0);  
    int senz1 = digitalRead(A1);  
  
    if (senz1 == LOW && senz2 == HIGH) {  
        analogWrite(LM1, sp2);  
        analogWrite(LM2, 0);  
        analogWrite(RM1, 0);  
        analogWrite(RM2, sp2);  
    } else if (senz1 == HIGH && senz2 == LOW) {  
        analogWrite(LM1, 0);  
        analogWrite(LM2, sp2);  
        analogWrite(RM1, sp2);  
        analogWrite(RM2, 0);  
    } else {  
        analogWrite(LM1, sp1);  
        analogWrite(LM2, 0);  
        analogWrite(RM1, sp1);  
        analogWrite(RM2, 0);  
    }  
}
```